

High Dynamic Range Image Reconstruction via Deep Explicit Polynomial Curve Estimation

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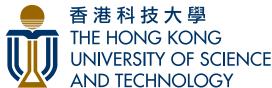
Paper: https://arxiv.org/abs/2307.16426

Project Page: https://github.com/jqtangust/EPCE-HDR

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Oral











High Dynamic Range (HDR) Image Reconstruction



32-bits HDR image





8-bits SDR image

High Dynamic Range (HDR) Image Reconstruction

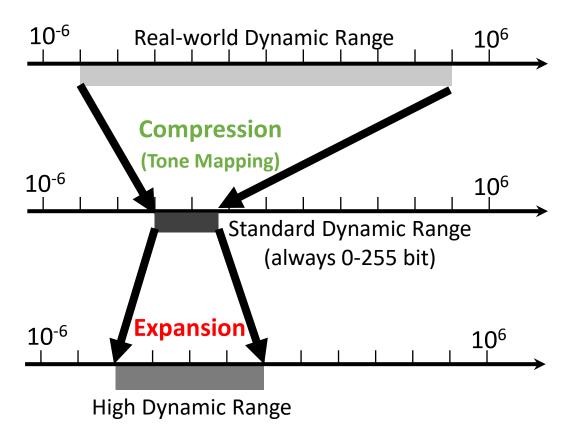


32-bits HDR image

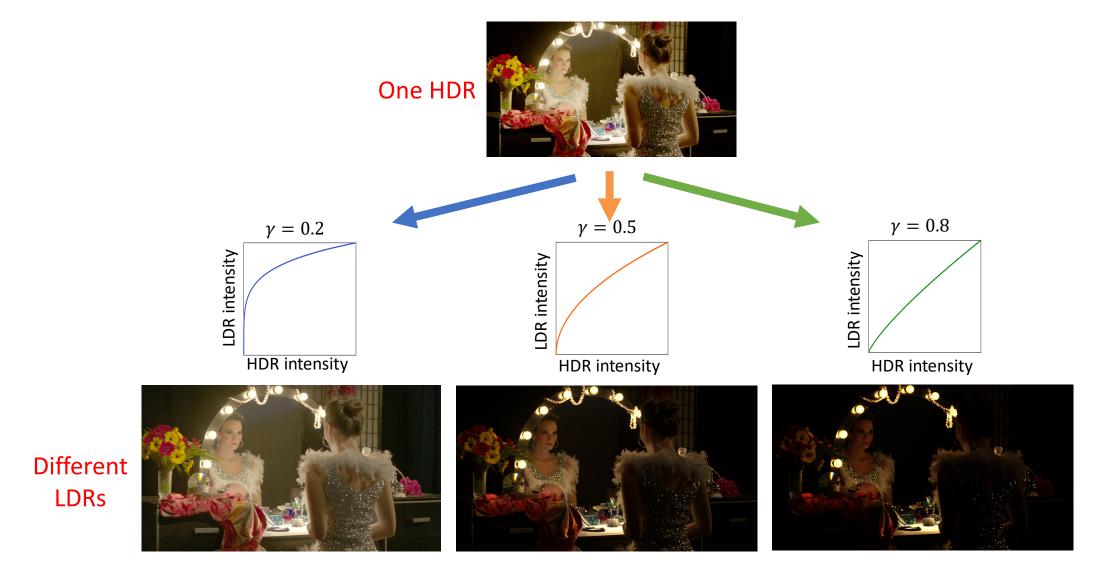




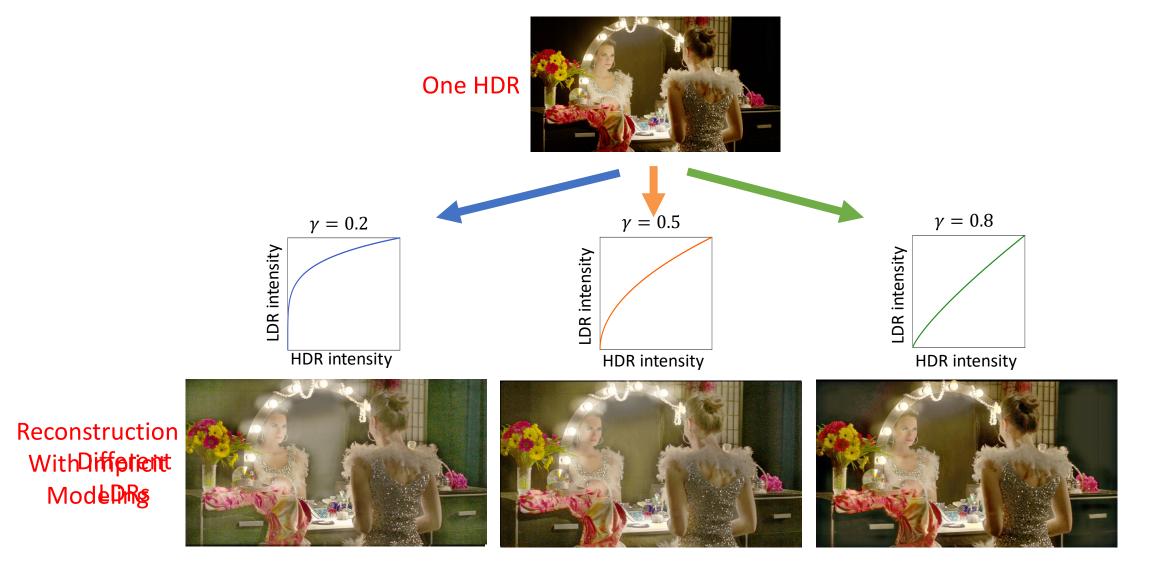
8-bits SDR image



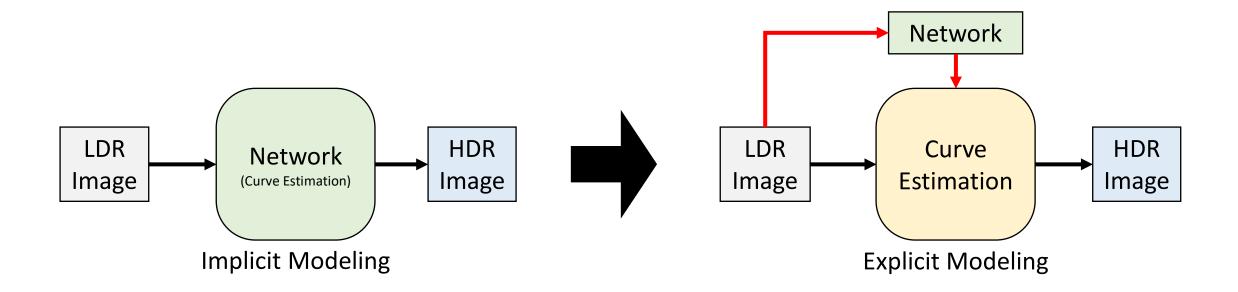
Practical Scenarios



Problems in Implicit Model: Incorrect Tone Mapping



Implicit Model vs. Explicit Model



Implicit Model vs. Explicit Model

Reconstruction
With Implicit
Modeling









Our
Reconstruction
With **Explicit**Modeling



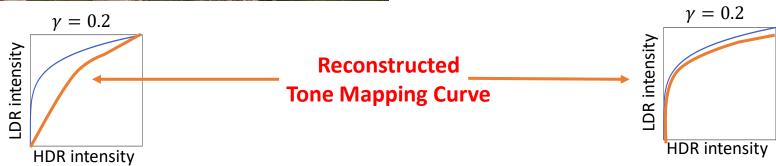




Implicit Model vs. Explicit Model







Our Contributions

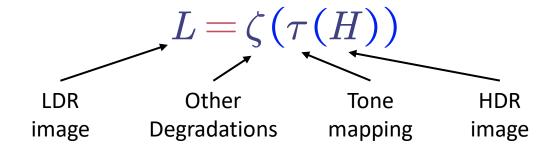
- A new framework
- → for handling diverse tone-mapping functions.

- A new synthetic dataset
- → clear relationship between LDR images and corresponding tone functions.

SOTA performance in synthesis and real datasets.

Reversing the Tone-Mapping Function

• HDR-to-LDR conversion (Camera Pipeline):



Reversing HDR-to-LDR conversion:

$$H = \tau^{-1}(\zeta^{-1}(L))$$

- Two Goals:
 - Reversing tone mapping function (Key)
 - > Removing other degradations

Parameterizing the Tone-Mapping Function

- What is structures of Tone mapping function?
- → Simple structure, monotonic or semi-monotonic curve.

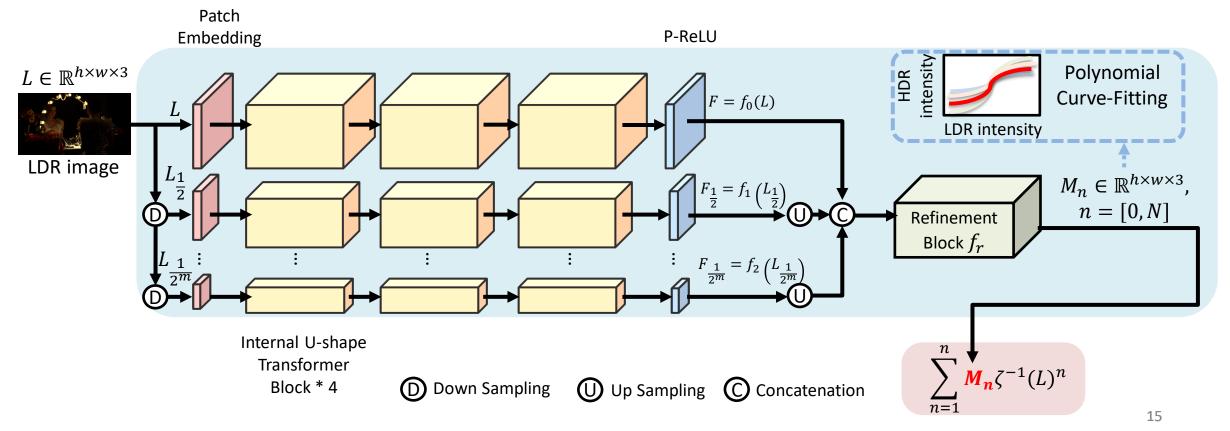
To parameterizing it as a polynomial curve:

$$H= au^{-1}(\zeta^{-1}(L))=\sum_{n=0}^N M_n\zeta^{-1}(L)^n$$
 $Polynomial$
 $Coefficient Maps$
 $(PCMs)$

Learning the Polynomial Coefficient Maps

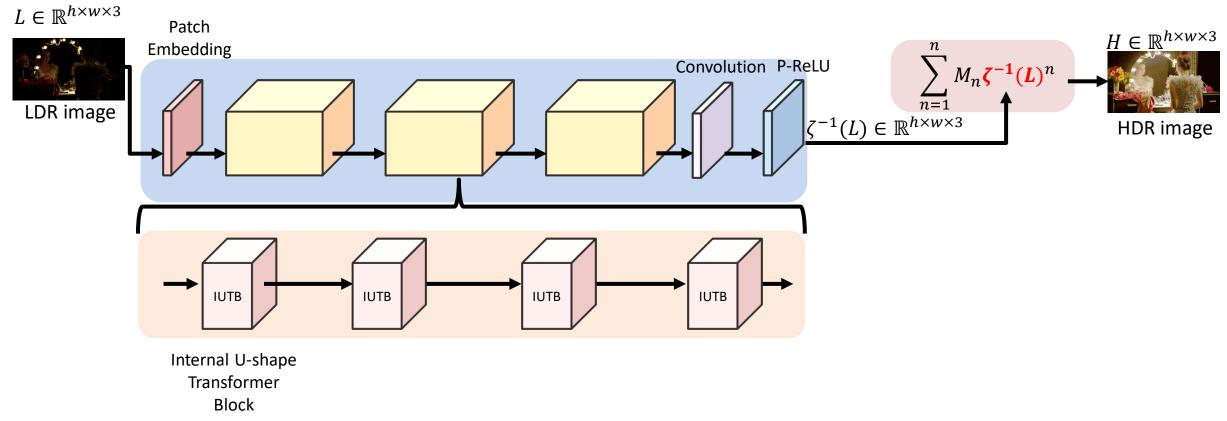
Pyramid-Path Vision Transformer (PPViT)

To fuse features from different scales.



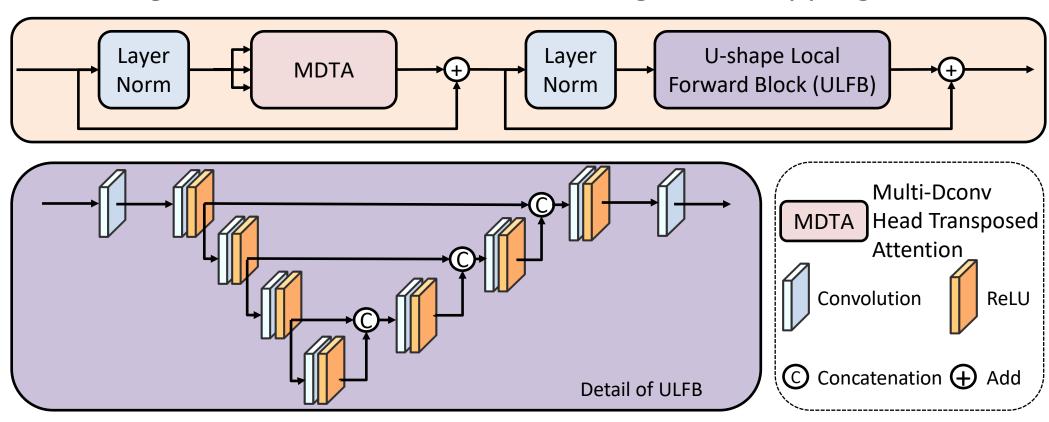
Removing other Degradations

Learnable Pixel-Wise Element (LPE) to remove other degradations.



Internal U-shape Transformer Block

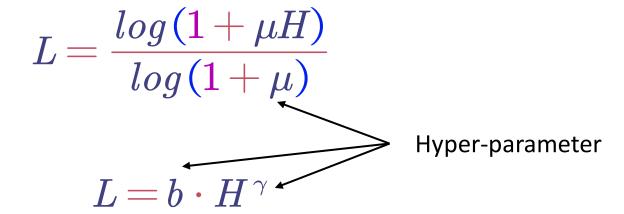
Extracting local information for estimating tone-mapping functions.

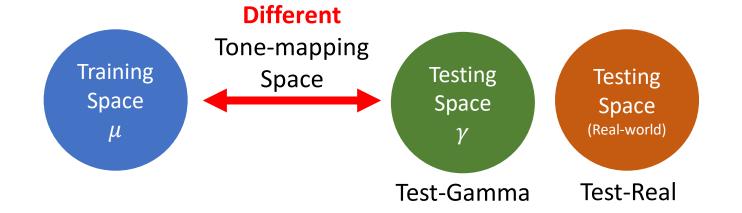


Dataset

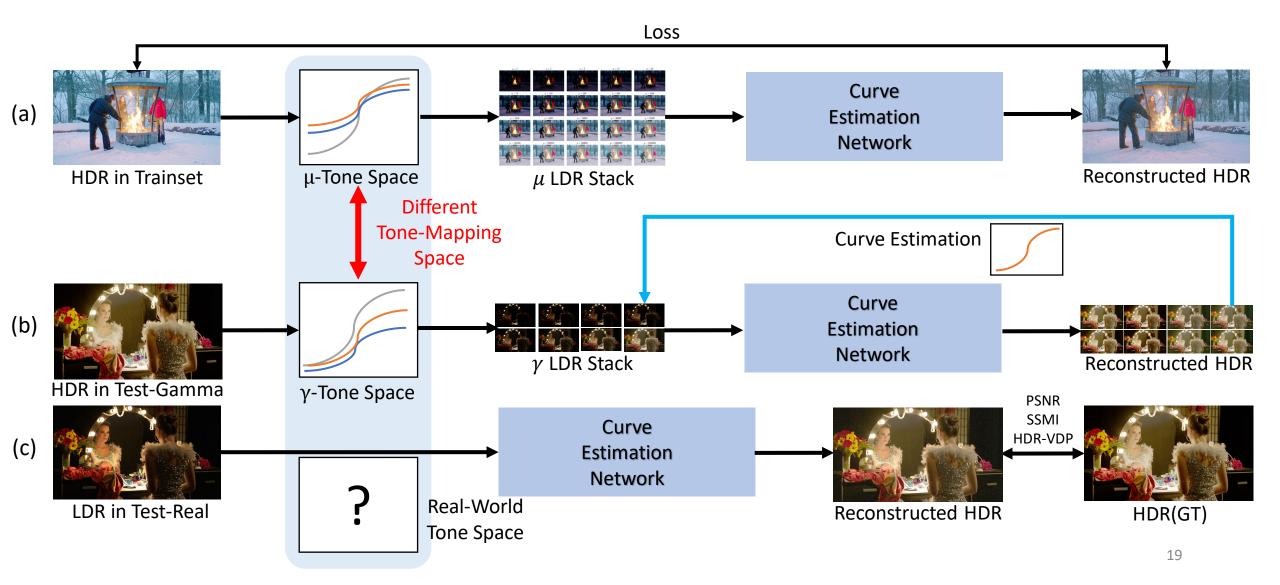
• Training at μ Space.

• Testing at γ Space.

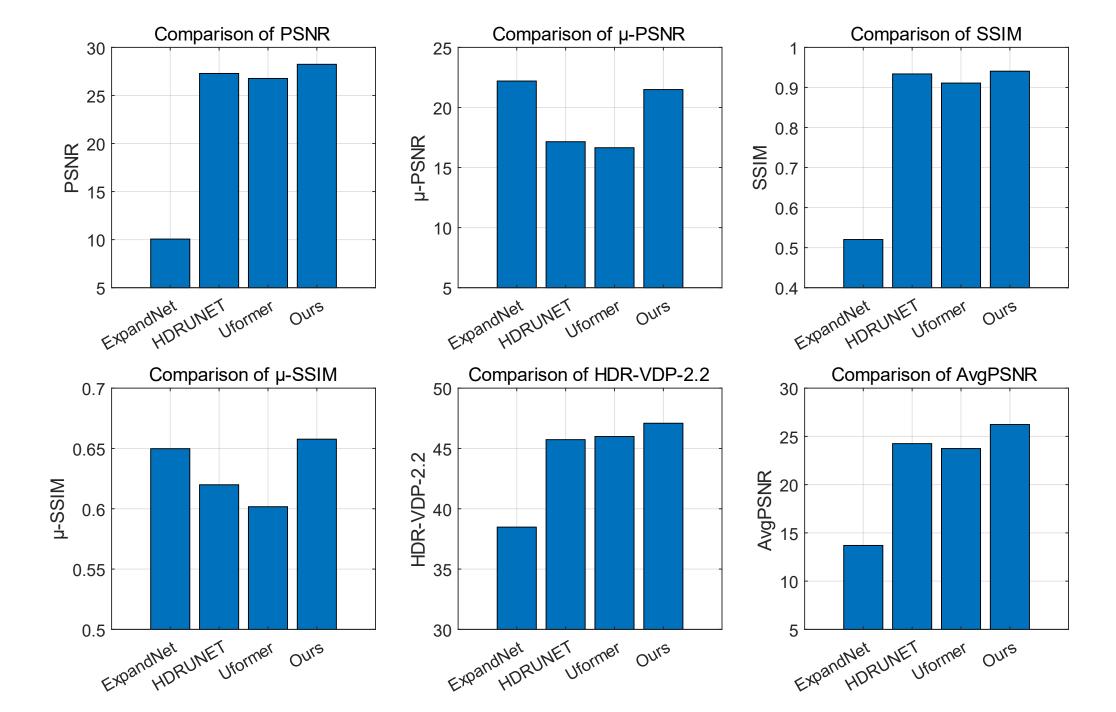




Training and Testing



Quantitative Comparison In **Test-Real** dataset



Qualitative Comparison In **Test-Real** dataset







ExpandNet

HDRUNET





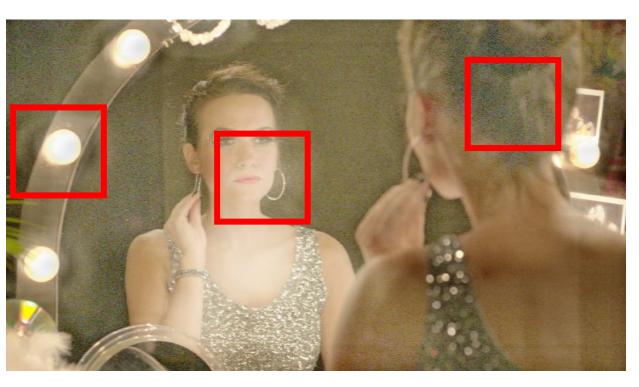


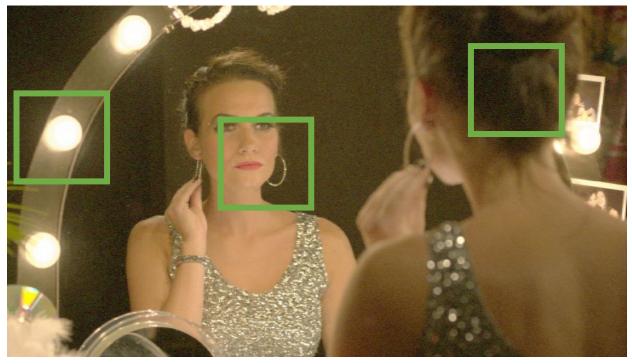
Uformer

Ours

Ground Truth

Details in Color Consistency





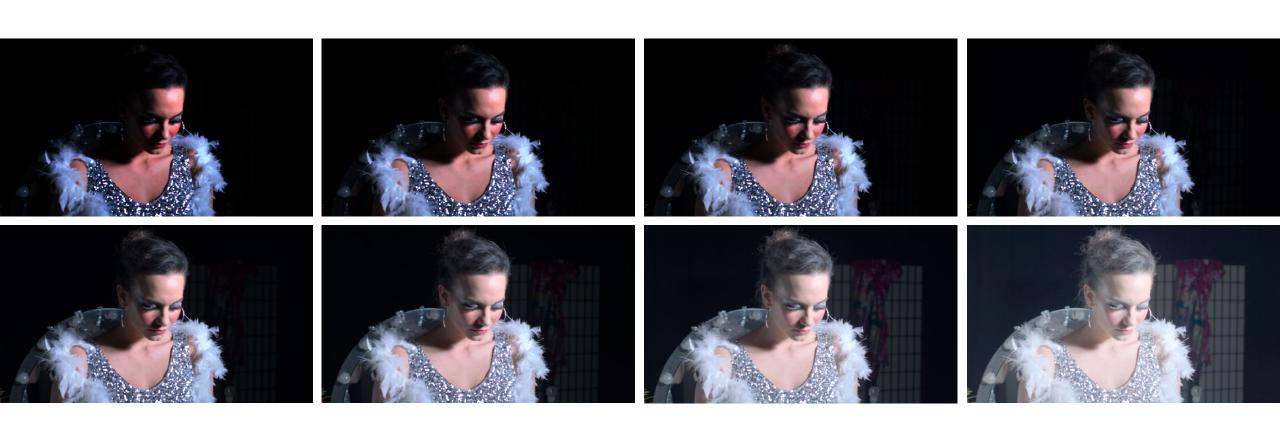
HDRUNET Ours

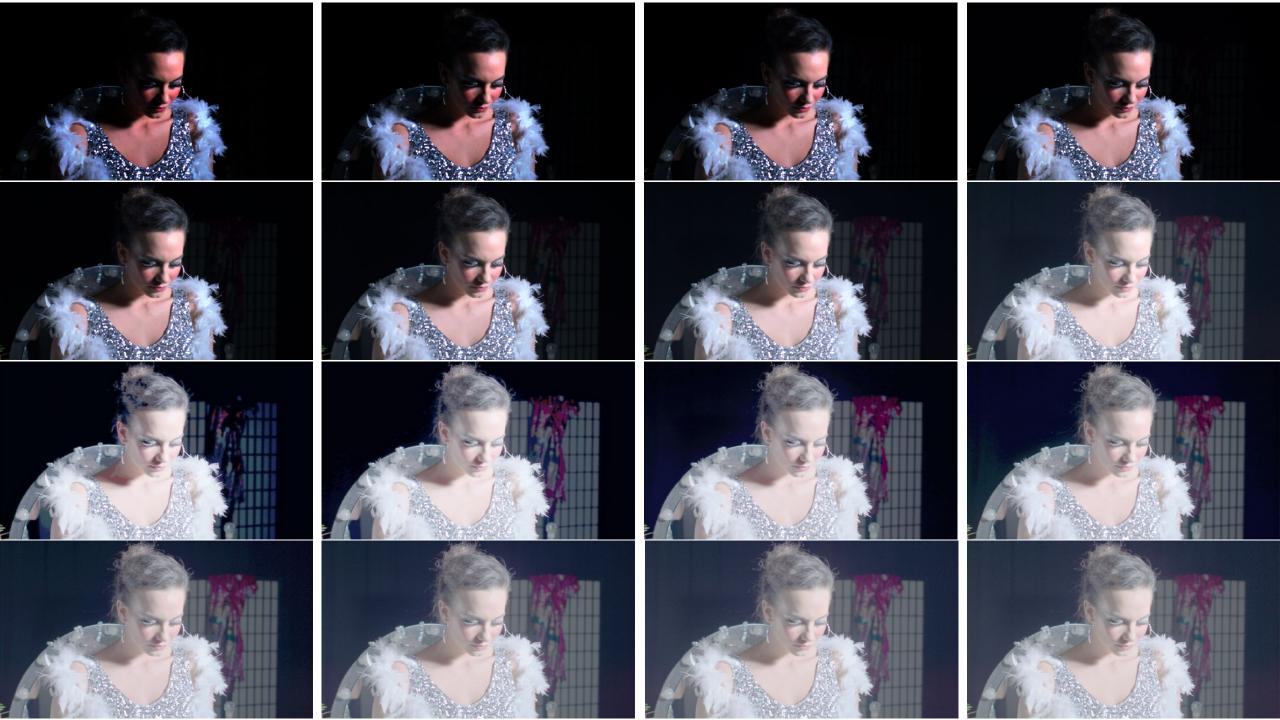
Qualitative Comparison

In **Test-Gamma** dataset

LDR image in Gamma Space

• The value of γ is from 0.2 to 1.

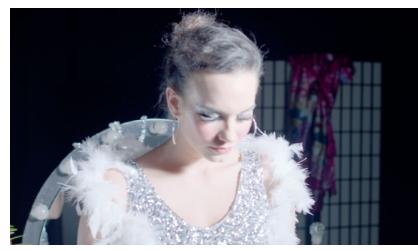




Comparison with HDRUNET







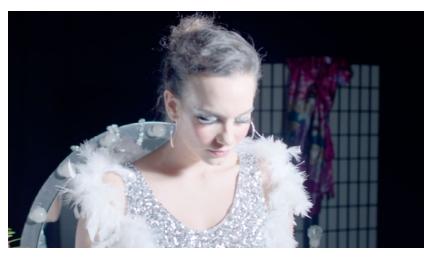
HDRUNET Ours Ground Truth

$$\gamma$$
 = 0.3

Comparison with HDRUNET







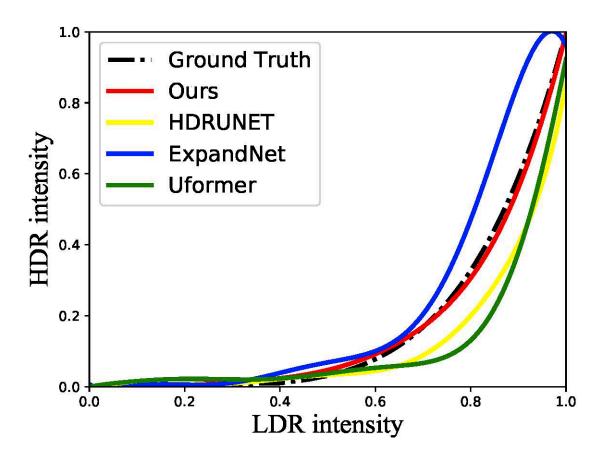
HDRUNET Ours Ground Truth

$$\gamma = 0.6$$

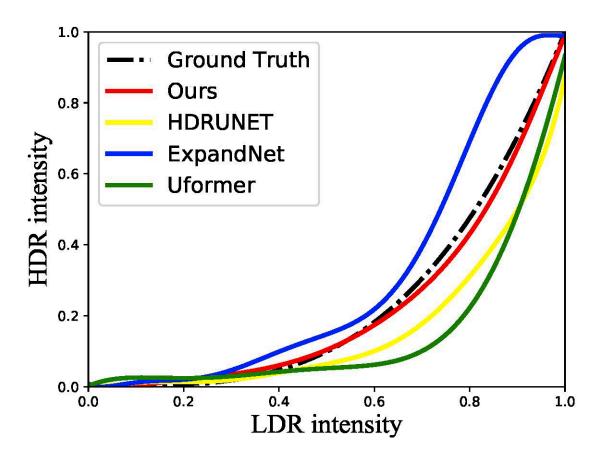
Comparison with HDRUNET



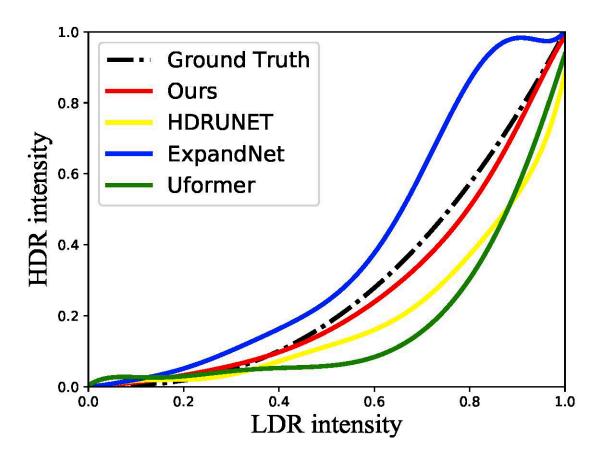
$$\gamma$$
 = 0.8



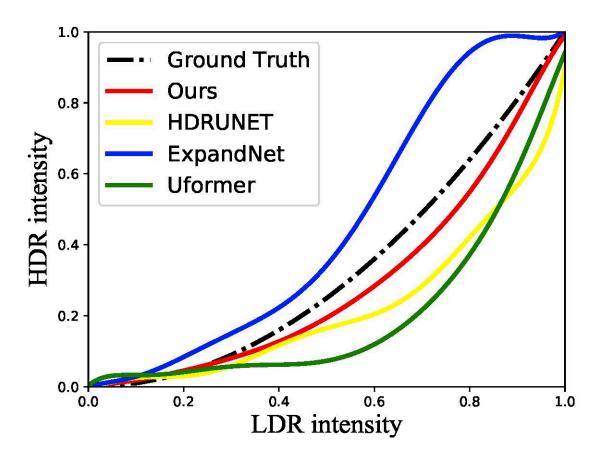
$$\gamma = 0.2$$



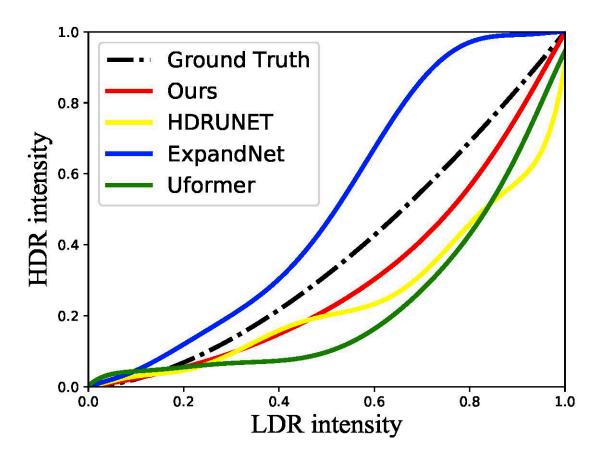
$$\gamma = 0.3$$



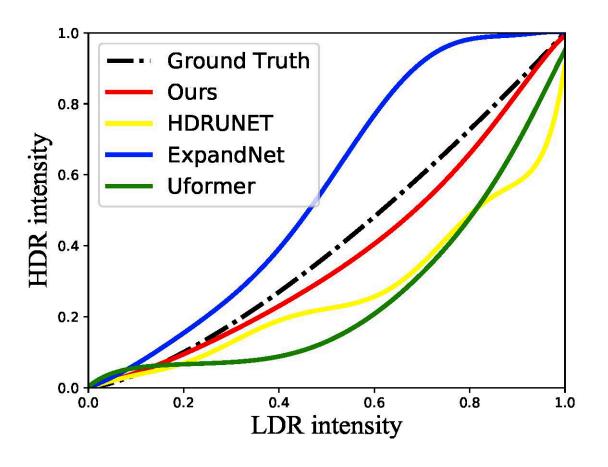
$$\gamma = 0.4$$



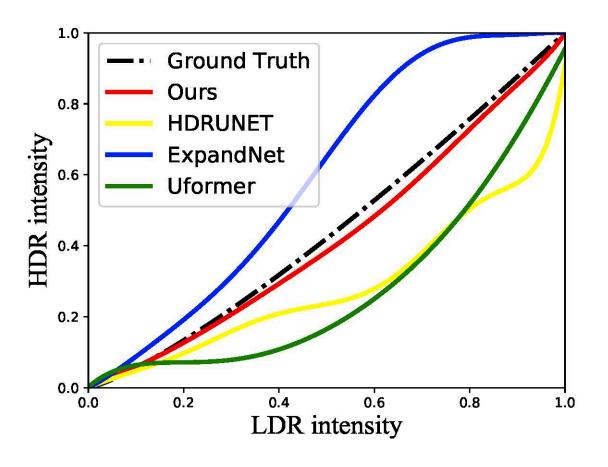
$$\gamma = 0.5$$



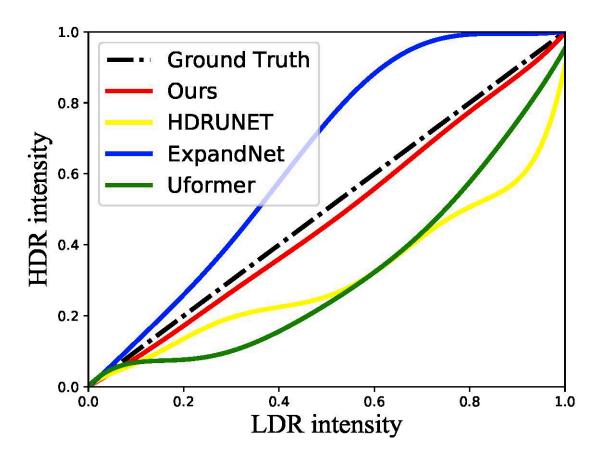
$$\gamma = 0.6$$



$$\gamma = 0.7$$



$$\gamma = 0.8$$



$$\gamma = 1.0$$

HDR Reconstruction in the Wild

























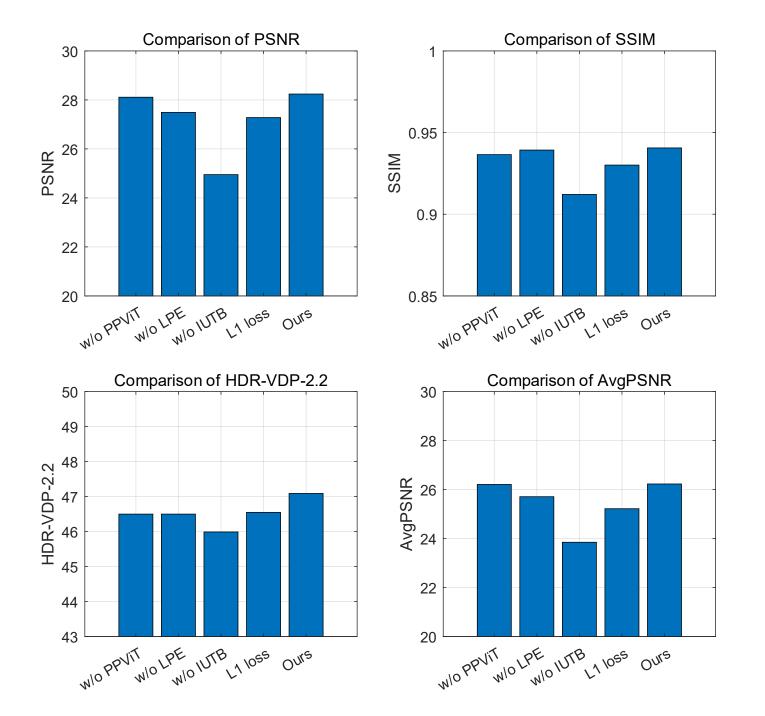








Ablation Study In **Test-Real** dataset



Limitations and Future Work

• Extreme tone mapping curves (e.g., gamma=0.2)







LDR

Reconstructed HDR

Ground Truth

- >Adopting a more flexible tone curve estimation strategy
- ➤ Providing a larger tone space in data or network

Conclusion

Explicit framework for HDR reconstruction

SOTA performance

 Useful for real-world HDR reconstruction in various practical scenarios.

Thanks

3/10/2023



Project Page



My LinkedIn